

MATH 320 NOTES, WEEK 10

Section 2.5 Change of Coordinate Matrix.

Recall that $I_V : V \rightarrow V$ is the identity linear transformation, i.e. $I_V(x) = x$ for all $x \in V$.

Theorem 1. *Suppose V is finite dimensional vector space and β, α are two bases for V . The change of coordinate matrix from α to β , $Q = [I_V]_{\alpha}^{\beta}$ is such that:*

- (1) for every vector $x \in V$, $Q[x]_{\alpha} = [x]_{\beta}$,
- (2) Q is invertible and $Q^{-1} = [I_V]_{\beta}^{\alpha}$,
- (3) If $T : V \rightarrow V$ is a linear transformation, then $[T]_{\alpha} = Q^{-1}[T]_{\beta}Q$

Proof. For simplicity, denote I_V simply by I . (1) follows since

$$Q[x]_{\alpha} = [I]_{\alpha}^{\beta}[x]_{\alpha} = [I(x)]_{\beta} = [x]_{\beta}.$$

(2): Q is invertible because I_V is invertible. Also, by 2.3,

$$[I]_{\beta}^{\alpha}Q = [I]_{\beta}^{\alpha}[I]_{\alpha}^{\beta} = [II]_{\alpha} = [I]_{\alpha} = I_n.$$

Similarly, $Q[I]_{\beta}^{\alpha} = I_n$. So $Q^{-1} = [I]_{\beta}^{\alpha}$.

(3): By 2.3, $[T]_{\alpha} = [IT]_{\alpha} = [I]_{\beta}^{\alpha}[T]_{\beta}[I]_{\alpha}^{\beta} = Q^{-1}[T]_{\beta}Q$. □

Computing the change of coordinate matrix:

Let $\alpha = \{x_1, \dots, x_n\}$ and $\beta = \{y_1, \dots, y_n\}$. Then the change of coordinate matrix Q from α to β is such that the i -th column of Q is $[x_i]_{\beta}$.

Example: In \mathbb{R}^3 , let $\alpha = \{(1, 1, 1), (0, 0, -2), (0, 1, 1)\}$, $\beta = \{(1, 0, 1), (3, 0, 0), (1, 1, 0)\}$, and $e = \{e_1, e_2, e_3\}$.

(1) Let's compute the change of coordinate matrix from α to β :

- $(1, 1, 1) = 1(1, 0, 1) - \frac{1}{3}(3, 0, 0) + 1(1, 1, 0)$
- $(0, 0, -2) = -2(1, 0, 1) + \frac{2}{3}(3, 0, 0) + 0(1, 1, 0)$
- $(0, 1, 1) = 1(1, 0, 1) - \frac{2}{3}(3, 0, 0) + 1(1, 1, 0)$

So, the matrix is
$$\begin{pmatrix} 1 & -2 & 1 \\ -\frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \\ 1 & 0 & 1 \end{pmatrix}$$

(2) The change of coordinate matrix from α to e is $A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & -2 & 1 \end{pmatrix}$

- (3) The change of coordinate matrix from e to α is $B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} \\ -1 & 1 & 0 \end{pmatrix}$

Note that $AB = BA = I_3$, i.e. $B = A^{-1}$.

- (4) The change of coordinate matrix from β to e is $\begin{pmatrix} 1 & 3 & 1 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$

Definition 2. Suppose that $A, B \in M_{n,n}(F)$. We say that A and B are **similar** if there is an invertible matrix Q such that $A = Q^{-1}BQ$. We write $A \sim B$

As an exercise, prove the following:

Problem 1. Being similar is an equivalence relation on matrices. I.e. it is reflexive, symmetric and transitive.

Problem 2. Suppose that $T : V \rightarrow V$ is a linear transformation, V is finite dimensional, and α, β are two bases for V . Then $[T]_\alpha$ and $[T]_\beta$ are similar matrices.

Review of chapter 2

Let $T : V \rightarrow W$ be a linear transformation, V, W vector spaces over F .

- (1) The dimension theorem: $\dim(V) = \text{nullity}(T) + \text{rank}(T)$.
- (2) If V, W have the same finite dimension, T is one-to-one iff onto.
- (3) T is invertible iff T is one-to-one and onto iff V, W are isomorphic. Then we write $V \cong W$.
- (4) If $\dim(V) = n$, then $V \cong F^n$.
- (5) If $\dim(V) = \dim(W)$, then $V \cong W$.

Notation and more facts:

- (1) If $\dim(V) = n$ and β is a basis for V , then $[x]_\beta \in F^n$ is the coordinate vector of x relative to β , and $\phi_\beta : V \rightarrow F^n$ defined by $\phi_\beta(x) = [x]_\beta$ is an isomorphism (i.e. it's one-to-one, onto, and linear).
- (2) If $T : V \rightarrow W$ linear, V, W finite dimensional, β is a basis for V , γ is a basis for W , then $[T]_\beta^\gamma$ is the corresponding matrix representation and for any $x \in V$,

$$[T]_\beta^\gamma [x]_\beta = [T(x)]_\gamma.$$

- (3) If $T : V \rightarrow W$ and $U : W \rightarrow Z$ are linear transformation, then so is $UT : V \rightarrow Z$ defined by $UT(x) = U(T(x))$, and if α, β, γ are bases for V, U, Z , respectively, then

$$[U]_\beta^\gamma [T]_\alpha^\beta = [UT]_\alpha^\gamma.$$

- (4) If A is n by n and e is the standard basis for F^n , then $[L_A]_e = A$.
(L_A denotes multiplication by A .)

Inverses:

If $T : V \rightarrow W$ is a one-to-one, onto linear transformation, then its **inverse** is $T^{-1} : W \rightarrow V$ defined by

$$T^{-1}(y) = x \text{ iff } T(x) = y.$$

An $n \times n$ matrix A is **invertible** if there is an $n \times n$ matrix B , such that $AB = BA = I_n$. Then we write $B = A^{-1}$.

Lemma 3. A is invertible iff L_A is invertible

Lemma 4. Let $\dim(V) = \dim(W) = n$, and $T : V \rightarrow W$ be a linear transformation, β any basis for V , γ any basis for W . Then T is invertible iff $[T]_\beta^\gamma$ is invertible.

Also, in that case, if $A = [T]_\beta^\gamma$, then $A^{-1} = [T^{-1}]_\gamma^\beta$.